

Abstract

Described are a method and a device for determining the position and/or the anticipated position of a vehicle (10) during a parking operation in relation to the oncoming lane (16) of a multi-lane roadway.

The object is to provide a method and a device which recognize the protrusion of a vehicle (10) into the oncoming lane (16) of a multi-lane roadway during a parking operation in a timely manner and, if necessary, activate suitable means for preventing the protrusion into the oncoming lane (16).

Due to the fact that the position of the oncoming lane (16) in relation to the vehicle (10) at the beginning of the parking operation, the anticipated parking trajectory of the vehicle (10), and potential intersections of the anticipated parking trajectory with the oncoming lane (16) are determined, a signal may be provided in the presence of at least one intersection of the parking trajectory with the oncoming lane (16); the signal may be processed into an alert of the driver of the vehicle (10) or into a timely deceleration of the vehicle (10).

(Figure 2)